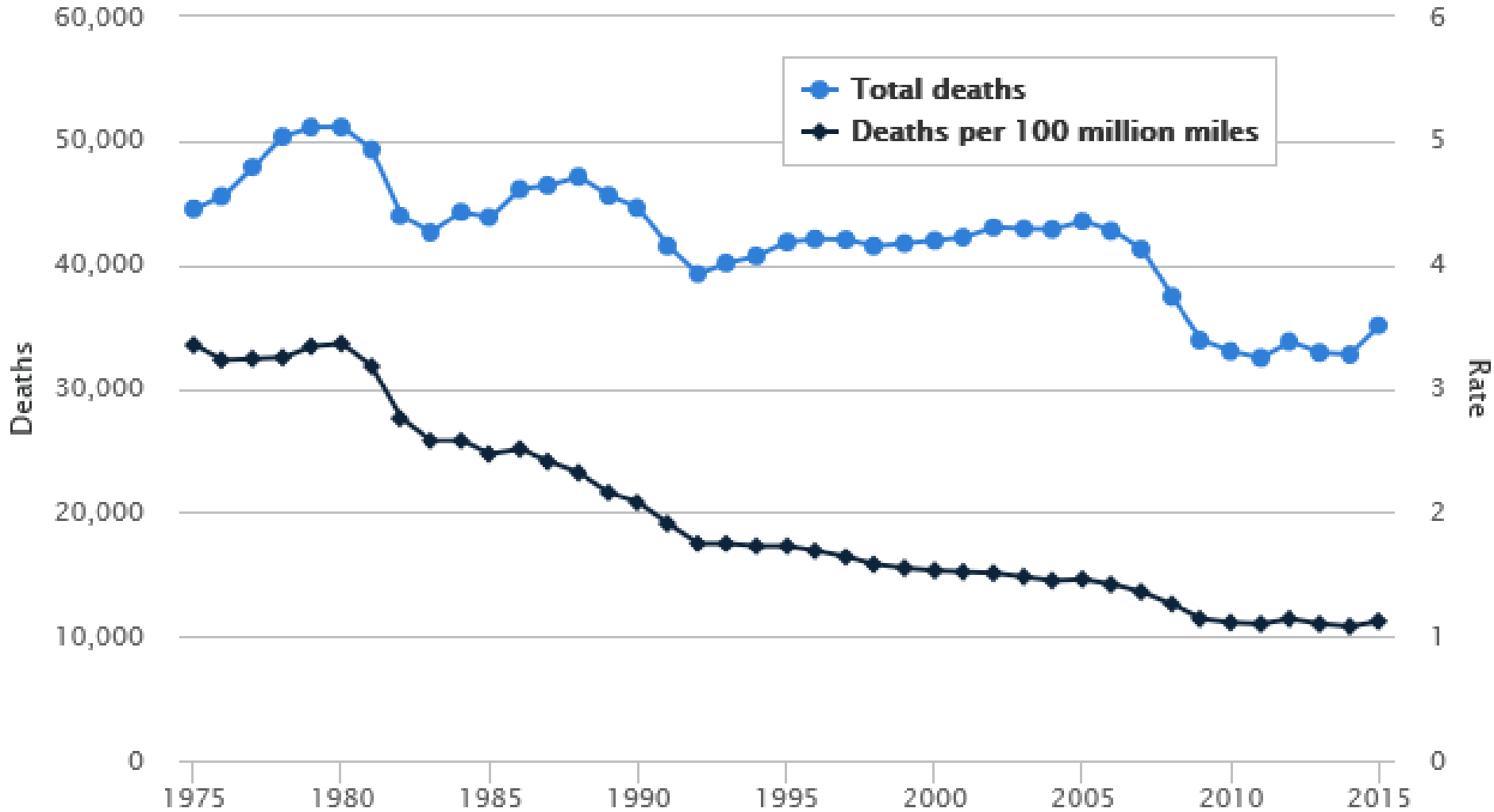


Connected and Automated Vehicle Realities

December 11, 2019

Motor vehicle crash deaths and deaths per 100 million miles traveled, 1975-2015



2016: 37,806
 2017: 37,133
 2018: 36,750

Source: Insurance Institute for Highway Safety & National Highway Traffic Safety Administration



The 5 levels of driving automation

For on-road vehicles



Human driver



Automated system

		Steering and acceleration/ deceleration	Monitoring of driving environment	Fallback when automation fails	Automated system is in control
Human driver monitors the road	0 NO AUTOMATION				N/A
	1 DRIVER ASSISTANCE				SOME DRIVING MODES
	2 PARTIAL AUTOMATION				SOME DRIVING MODES
Automated driving system monitors the road	3 CONDITIONAL AUTOMATION				SOME DRIVING MODES
	4 HIGH AUTOMATION				SOME DRIVING MODES
	5 FULL AUTOMATION				



Input Variables

- Level 4 Capabilities = 2019
- Level 4/5 Passenger Vehicles = 2023
- Level 4/5 Every New Passenger Vehicle = 2030
- Median Fleet Age = 11.5 years
- Fleet Turnover = 23 years

Equation

$$2030 + 23 = \dots\dots\dots 2053$$

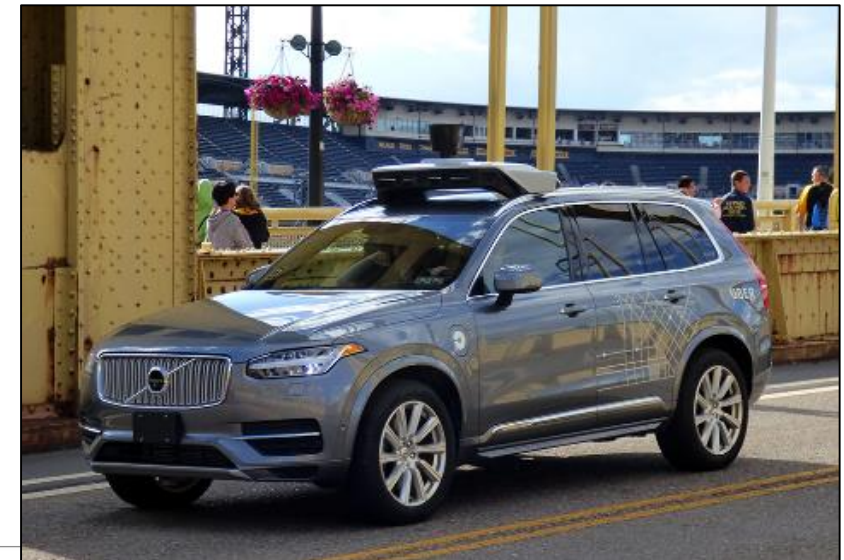


Exhibit 11 Vehicle Technology Deployment Summary

Technology	Deployment Cycle	Typical Cost Premium	Market Saturation Share
Automatic transmissions	50 years (1940s-90s)	\$1,500	90% U.S., 50% worldwide
Air bags	25 years (1973-98)	A few hundred dollars	100%, due to federal mandate
Hybrid vehicles	25+ years (1990s-2015+)	\$5,000	Uncertain. Currently about 4%.
Subscription services	15 years	\$250 annual	2-5%
Navigation systems	30+ years (1985-2015+)	\$500 and rapidly declining	Uncertain; probably over 80%.

New technologies usually require several decades between commercial availability to market saturation.

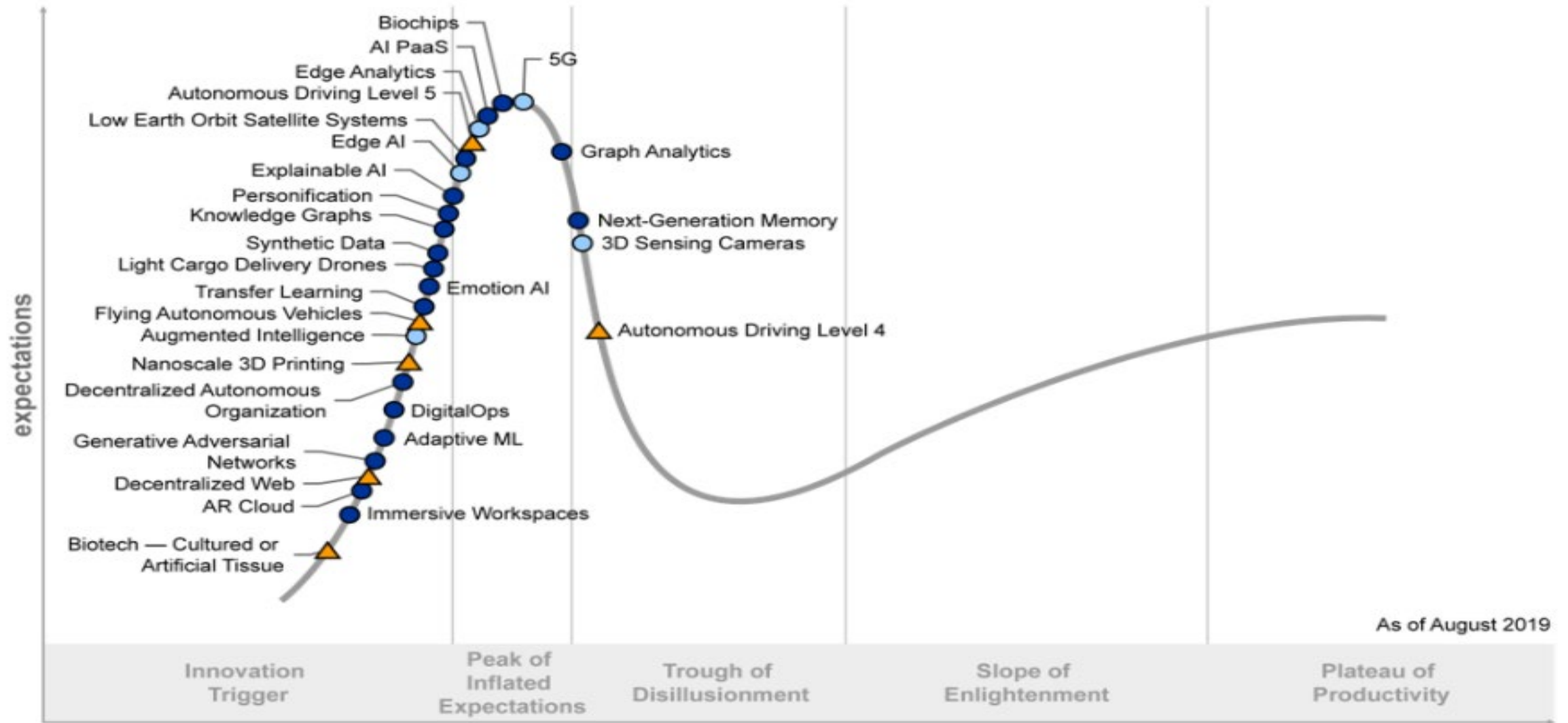
Exhibit 13 Autonomous Vehicle Market Penetration Projections

Stage	Decade	New Sales	Fleet	Travel
Available with large price premium	2020s	2-5%	1-2%	1-4%
Available with moderate price premium	2030s	20-40%	10-20%	10-30%
Available with minimal price premium	2040s	40-60%	20-40%	30-50%
Standard feature included on most new vehicles	2050s	80-100%	40-60%	50-80%
Saturation (everybody who wants it has it)	2060s	?	?	?
Required for all new and operating vehicles	???	100%	100%	100%

Autonomous vehicle will probably take several decades to penetrate new vehicle sales, fleets and total vehicle travel.

Source: Victoria Transport Policy Institute



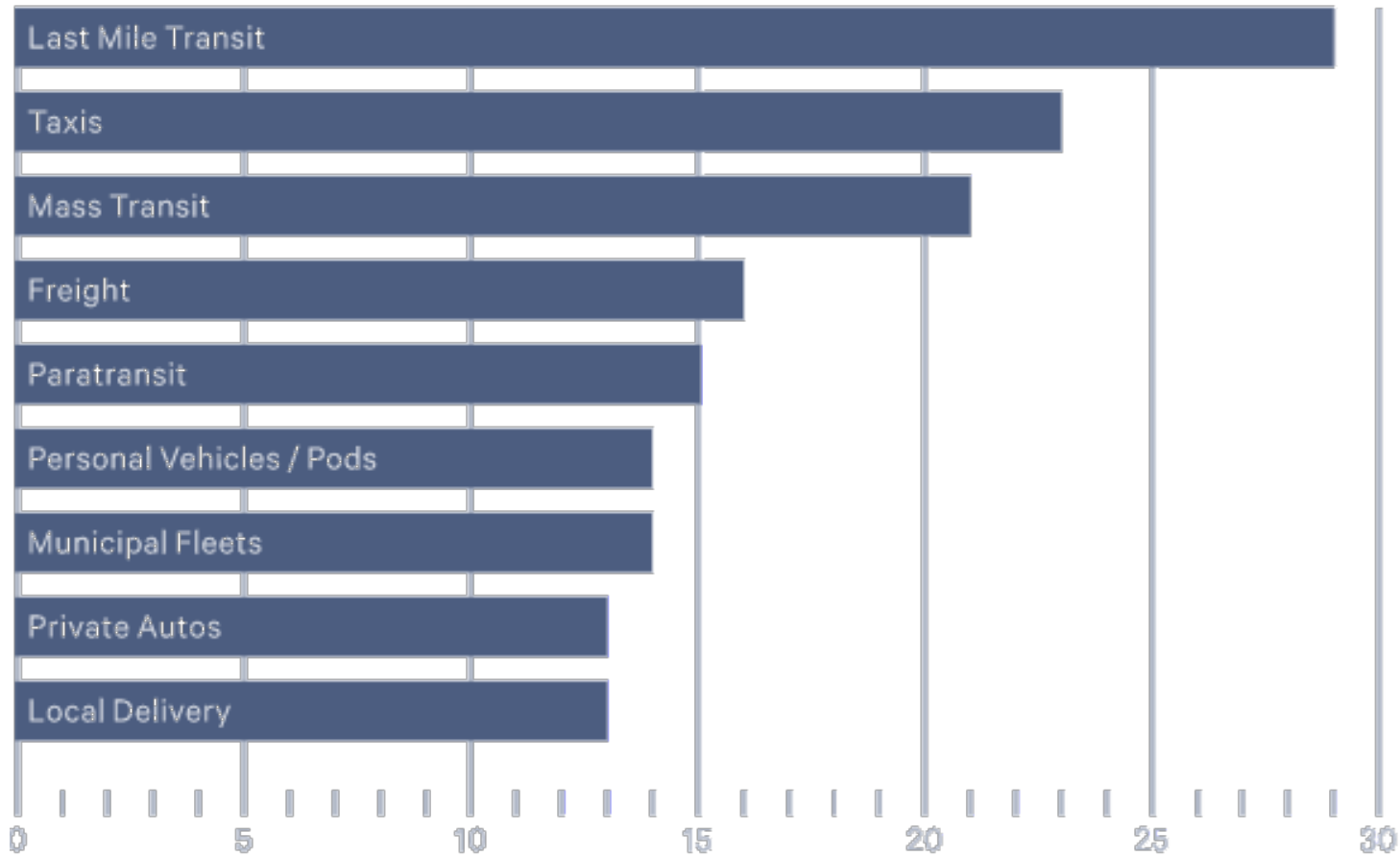


Plateau will be reached:

- less than 2 years
- ◐ 2 to 5 years
- 5 to 10 years
- ▲ more than 10 years
- ⊗ obsolete before plateau



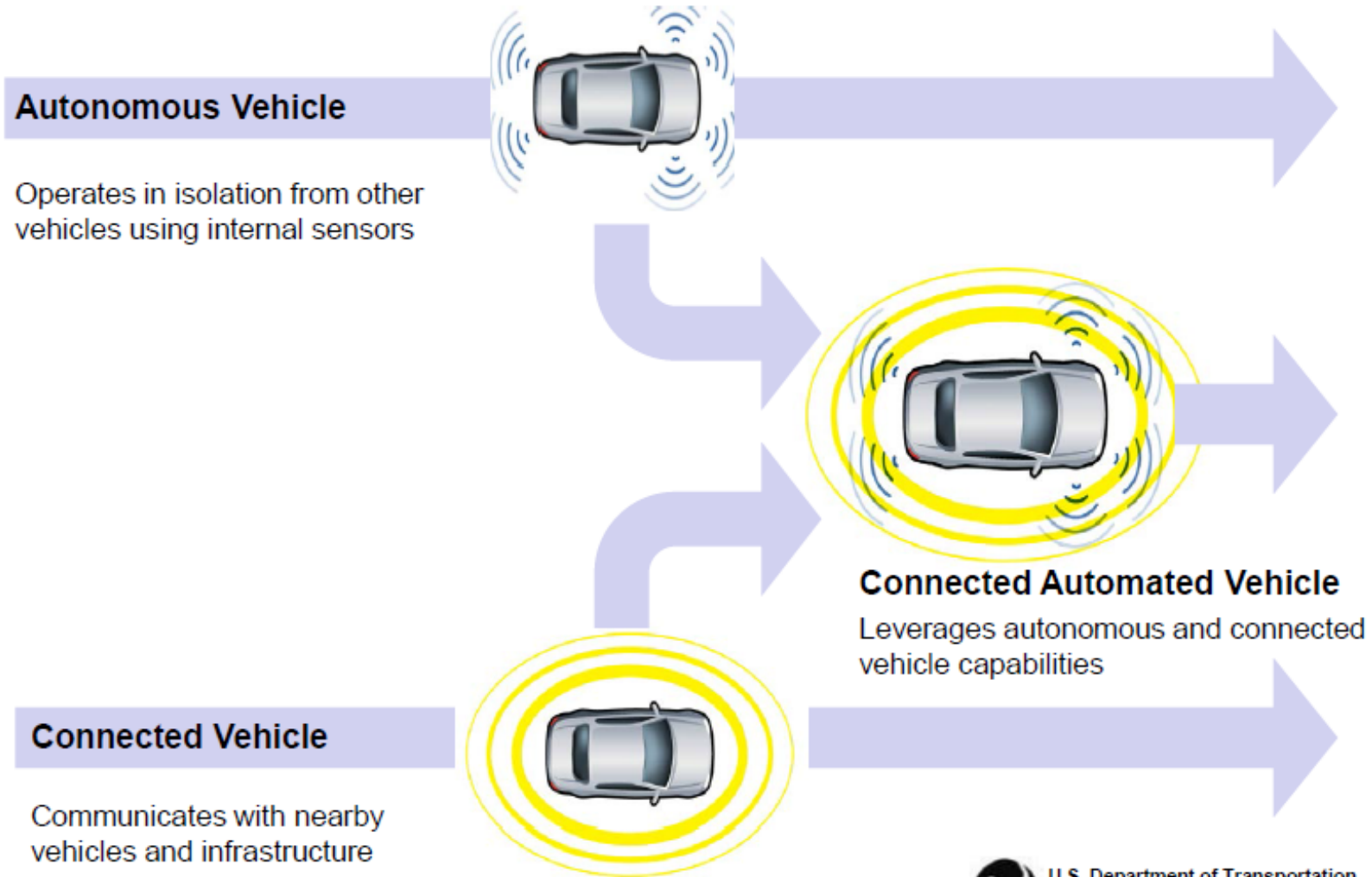
Anticipated AV Use Cases

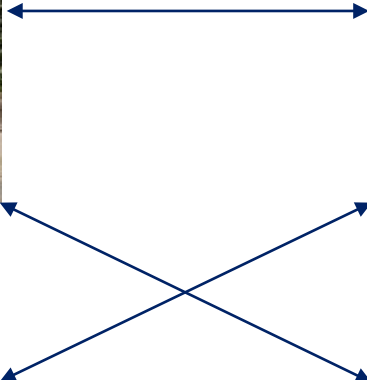


Source: Bloomberg.org

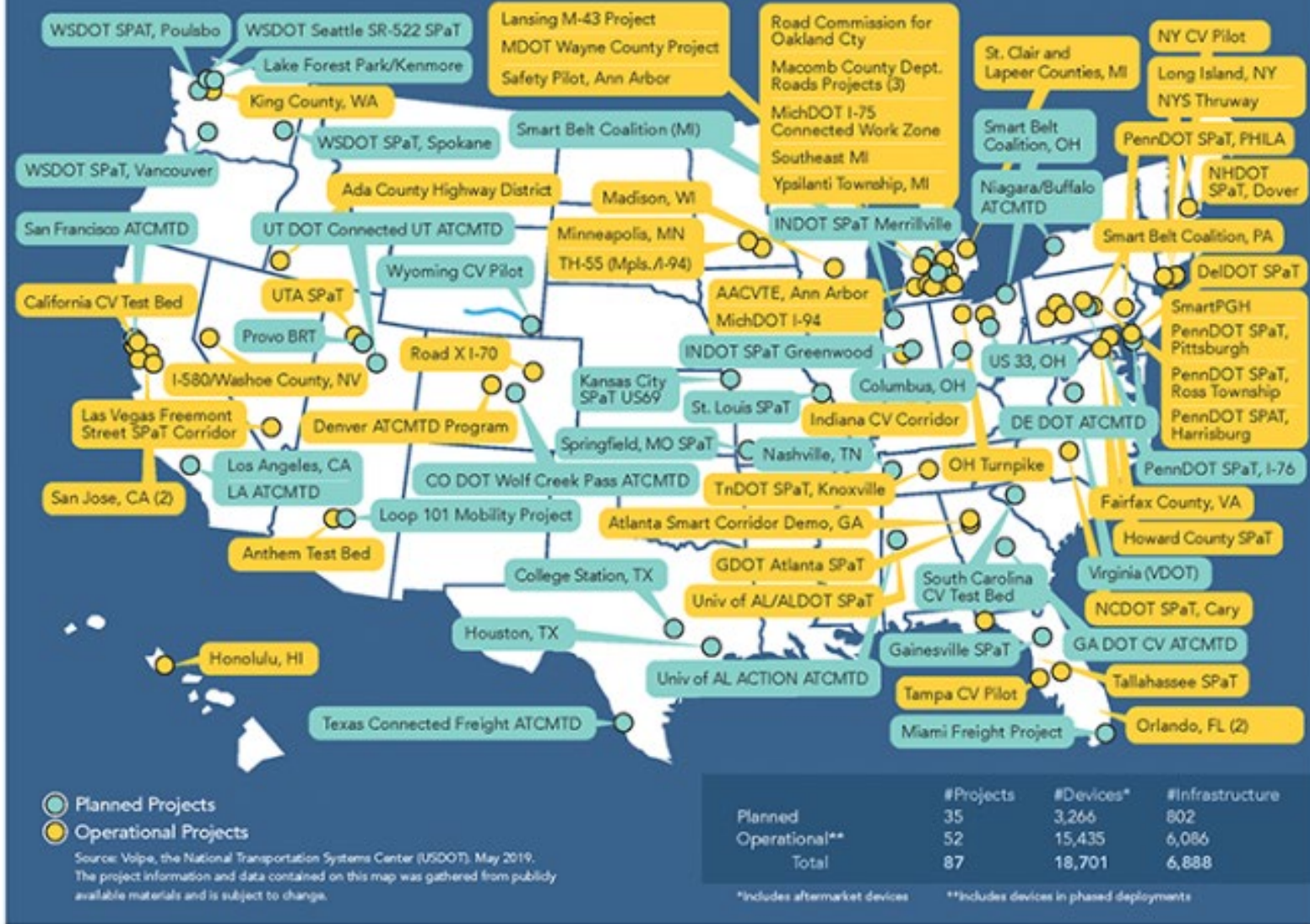


Connected Vehicles / Automated Vehicles





Uses of the 5.9 GHz band: Connected Vehicle Deployment Locations – Planned and Operational



Source: USDOT



V2X Technology

Crash reduction and environmental improvement while adhering to regulations in each region

TOYOTA supports interoperable, fully-validated and government-supported V2X technologies.

V2X Short Range Environment

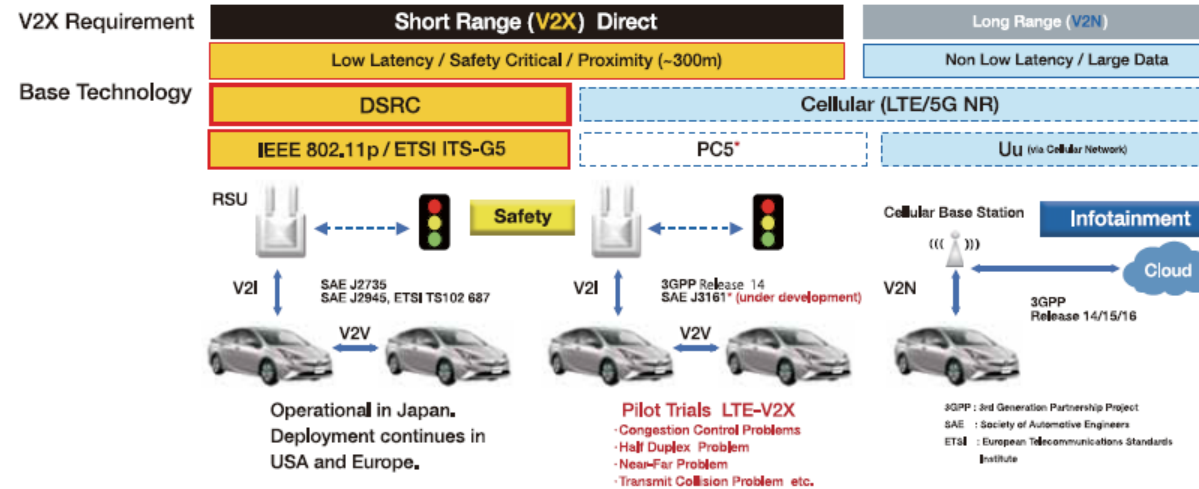
Estimation by TOYOTA

	Japan 	USA 	Europe 	China 	Australia 
V2X Technology	DSRC (ITS Connect)	DSRC	DSRC (ITS-G5)	LTE-V2X	DSRC / LTE-V2X
Frequency	760 MHz 755-765 MHz	5.9 GHz 5,850-5,925 GHz	5.9 GHz 5,855-5,925 GHz	5.9 GHz 5,905-5,925 GHz	5.9 GHz 5,855-5,925 GHz
Deployment Status	Commercial	Operational	Announcement	Pilot	Proof of Concept

V2X Hybrid Communication

Using both DSRC and Cellular Appropriately

Vehicle-to-everything (V2X) connectivity is achieved with a combination of **Short-range direct communication (DSRC for Safety)** and Long-range network communication (Cellular-V2N) – “Hybrid Communication”.



TOYOTA



Technology and Travel Behavior

How Transportation Technology Could Impact Travel Demand



Challenges/Opportunities for Public Agencies

- Vehicles
- Signal System Upgrades
- Infrastructure Improvements
- Communications Networks
- Data Management
- Workforce Development
- Business Processes
- Cybersecurity
- Partnering
- Technology Advancement
- Regulatory Developments
- Financing/Business Models



Photo: psu.edu



Resources

NCHRP 20-102

Impacts of CVs and AVs on State and Local Transportation Agencies NCHRP Project 20-102 December 2017

The National Cooperative Highway Research Program (NCHRP) is an applied research program funded by the state departments of transportation that is managed by the Transportation Research Board, part of the National Academies of Sciences, Engineering and Medicine. NCHRP Project 20-102 began in December 2014 to tackle emerging CV/AV issues and has \$6M in funding to-date. Selection of tasks and conduct of research is being coordinated with U.S. DOT and private sector efforts. Search for NCHRP 20-102 or contact Ray Derr (rderr@nas.edu) for more information.

Reports Available

[Advancing Automated and Connected Vehicles: Policy and Planning Actions for State and Local Transportation Agencies](#) [NCHRP Report 845]
The report and accompanying [briefing document](#) present potential societal outcomes of these technologies along with 18 policy and planning strategies that agency and legislative decision-makers could apply to align AV and CV technologies with public policy interests more effectively.



[Impacts of Regulations and Policies on CV and AV Technology Introduction in Transit Operations](#) [NCHRP Web-Only Document 239]
The report describes a roadmap of activities by industry, legislatures, federal government, and others to facilitate automated transit deployment and accelerate the societal benefits. These activities address technology, safety, workforce, operating policies, laws and regulations, and implementation of research findings.

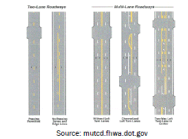


[Challenges to CV and AV Application in Truck Freight Operations](#) [NCHRP Web-Only Document 231]
The report describes freight environments and challenges for connected and highly automated technologies, identifies public and private sector barriers to implementation, and proposes next steps for addressing challenges.



Coming in 2018

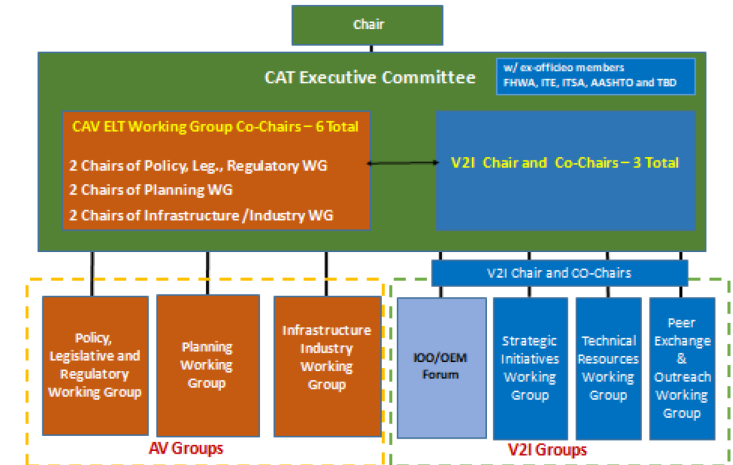
[Road Markings for Machine Vision](#) (Task 6) is developing information on the performance characteristics of longitudinal pavement markings (i.e., center lines, lane lines, edge lines, and dotted lines across freeway ramps) that affect the ability of machine vision systems to recognize them. This information will be used by the AASHTO/SAE Working Group as they develop guidelines and criteria. The report is expected in Q1 2018. Further work will be done on contrast markings and the effects of glare on two-lane roads.



TRANSPORTATION RESEARCH BOARD

The National Academies of
SCIENCES • ENGINEERING • MEDICINE

Cooperative Automated Transportation (CAT) Coalition



Thank you!

Matt Smith, P.E.
Matthew.smith@mbakerintl.com

