

PA Turnpike Connected Work Zone Pilot



Michael Pack
Pennsylvania Turnpike Commission

Dwight Shank
Iteris

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Agenda

- PA Turnpike CAV Roadmap – Selection of CV Pilot
- Connected Work Zone Pilot
 - Architecture
 - Evaluation Metrics
 - Installation and Integrations
 - Evaluation Preliminary Findings
 - Lessons Learned



CAV Roadmap

CAV Roadmap Project

- Project executed February 2016
- Prime – AECOM
- Subs – Information Logistics and TTI
- Roadmap Tasks:
 - Research current standards and best practices
 - Identify potential projects for short/mid/long term
 - Align with capabilities of PTC infrastructure readiness, planned projects, and in-house capabilities
 - Develop Implementation plan, starting with a “Quick Win” project
- Roadmap completed April 2017
- Executed CV pilot project December 2017



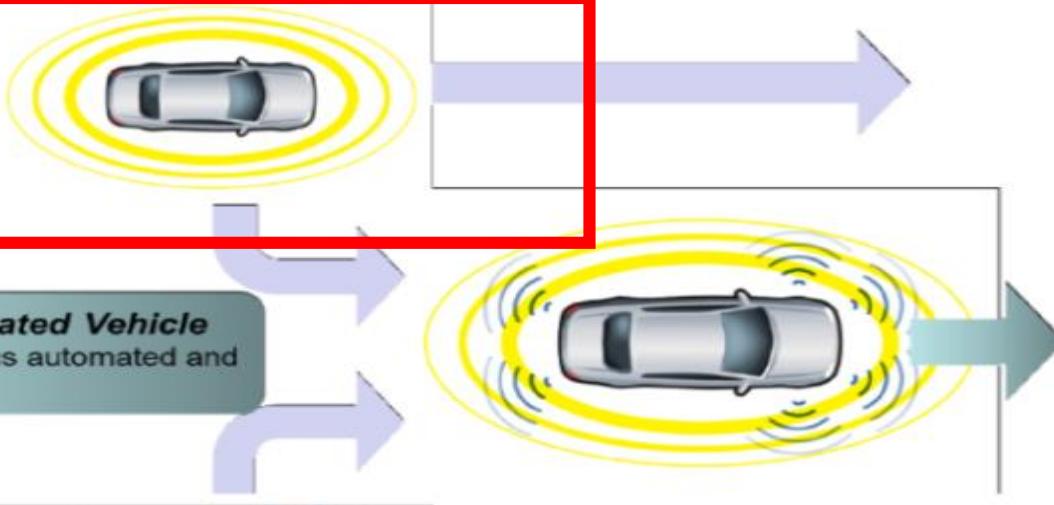
Application Areas

V2I Safety	Environment	Mobility
Red Light Violation Warning Curve Speed Warning Stop Sign Gap Assist Spot Weather Impact Warning Reduced Speed/Work Zone Warning Pedestrian in Signalized Crosswalk Warning (Transit)	Eco-Approach and Departure at Signalized Intersections Eco-Traffic Signal Timing Eco-Traffic Signal Priority Connected Eco-Driving Wireless Inductive/Resonance Charging Eco-Lanes Management Eco-Speed Harmonization Eco-Cooperative Adaptive Cruise Control Eco-Traveler Information Eco-Ramp Metering Low Emissions Zone Management AFV Charging / Fueling Information Eco-Smart Parking Dynamic Eco-Routing (light vehicle, transit, freight) Eco-ICM Decision Support System	Advanced Traveler Information System Intelligent Traffic Signal System (I-SIG) Signal Priority (transit, freight) Mobile Accessible Pedestrian Signal System (PED-SIG) Emergency Vehicle Preemption (PREEMPT) Dynamic Speed Harmonization (SPD-HARM) Queue Warning (Q-WARN) Cooperative Adaptive Cruise Control (CACC) Incident Scene Pre-Arrival Staging Guidance for Emergency Responders (RESP-STG) Incident Scene Work Zone Alerts for Drivers and Workers (INC-ZONE) Emergency Communications and Evacuation (EVAC) Connection Protection (T-CONNECT) Dynamic Transit Operations (T-DISP) Dynamic Ridesharing (D-RIDE) Freight-Specific Dynamic Travel Planning and Performance Drayage Optimization
V2V Safety	Agency Data	Smart Roadside
Emergency Electronic Brake Lights (EEBL) Forward Collision Warning (FCW) Intersection Movement Assist (IMA) Left Turn Assist (LTA) Blind Spot/Lane Change Warning (BSW/LCW) Do Not Pass Warning (DNPW) Vehicle Turning Right in Front of Bus Warning (Transit)	Probe-based Pavement Maintenance Probe-enabled Traffic Monitoring Vehicle Classification-based Traffic Studies CV-enabled Turning Movement & Intersection Analysis CV-enabled Origin-Destination Studies	Wireless Inspection Smart Truck Parking
Road Weather		

Connected vs Autonomous

Connected Vehicle

Communicates with nearby vehicles and infrastructure; Not automated



Autonomous Vehicle

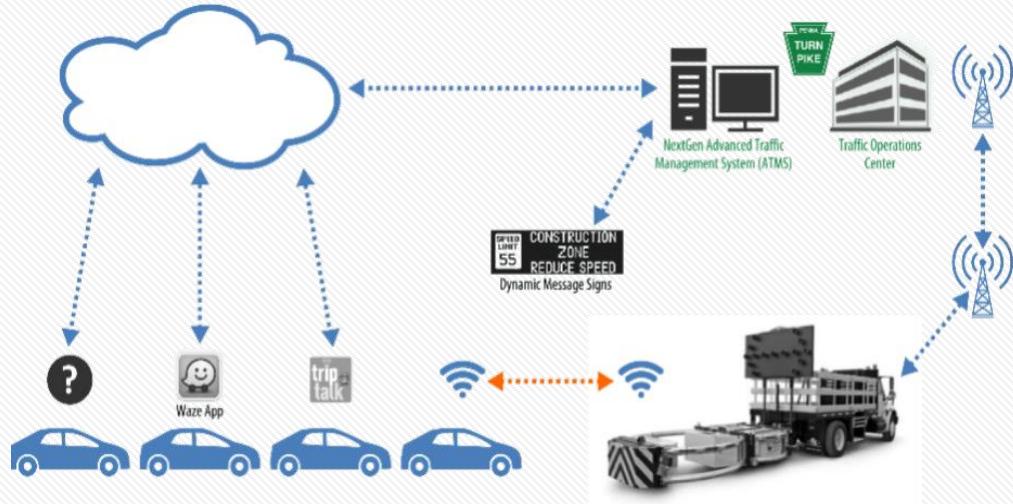
Operates in isolation from other vehicles using internal sensors



U.S. Department of Transportation

Figure 1. What are Connected and Automated Vehicles?

CV Top Priorities



CV Deployment Plan

Short-Term 0-4 Years ▶	Mid-Term 4-10 Years ▶	Long-Term Beyond 10 Years ▶
<ul style="list-style-type: none">• Warnings about Upcoming Work Zone (Work Zone Safety)• Advanced Traveler Information Systems (Traveler Information)• Incident Scene Work Zone Alerts for Drivers and Workers (Traffic Incident Management)• Electronic Toll Collection (Tolling)• Reduced Speed Zone Warning/Lane Closure (Work Zone Safety)• Traveler Information-Smart Parking (Traveler Information)• Curve Speed Warning (Roadway Safety)• Spot Weather Impact Warning (Road Weather Safety)	<ul style="list-style-type: none">• Incident Scene Pre-Arrival Staging Guidance for Emergency Responders (Traffic Incident Management)• Road Weather Information for Maintenance and Fleet Management Systems (Road Weather Safety)• Variable Speed Limits for Weather-Responsive Traffic Management (Road Weather Safety)• Road Weather Motorist Alert and Warning (Road Weather Safety)• In-Vehicle Signage (Traveler Information)• Queue Warning (Roadway Safety)• Warnings about Hazards in a Work Zone (Work Zone Safety)	<ul style="list-style-type: none">• Speed Harmonization (SPD-HARM) (Traffic Network)• Road Use Charging (Congestion Pricing)• Vehicle Data for Traffic Operations (Traffic Network)• Performance Monitoring and Planning (Traffic Network)• Enhanced Maintenance Decision Support System (Traffic Network)• Advanced Automatic Crash Notification Relay (EVAC) (Traffic Incident Management)• Road Weather Information and Routing Support for Emergency Responders (Traffic Incident Management)

Short Term Projects – Quick Wins

CAV Safety Core Focus Areas

Work Zone Safety

Traffic Incident Management

Roadway Safety

Road Weather Safety

CV Applications

- ▶ Warnings about Upcoming Work Zone
- ▶ Incident Scene Work Zone Alerts for Drivers and Workers
- ▶ Reduced Speed Zone Warning/Lane Closure
- ▶ Curve Speed Warning
- ▶ Spot Weather Impact Warning

“Quick Win” Projects

Option 1 (Pick One):

Mobile and Maintenance Patterns Warning (Line Painting; MP 319-326; MP 202-206)

Curve and Ramp Warning Systems (Breezewood Interchange)

Road Weather Information Systems (Mile Marker 288)

Option 2:

Connected Truck Mounted Attenuator Pilot



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Why Pilot CV for Work Zone?

Work Zone Crash Summary

Fiscal Year - Total*

Fiscal Year	Work Zone Total Crashes			Work Zone Fatal Crashes		Vehicle Miles Traveled (Crashes per MVMT)		Capital Spending (Crashes per Million)	
	Total	Injury	PDO**	Total	Person	MVMT	Rate	Cost (M)	Rate
FY2014	214	70	141	3	3	6,143.3	0.035	\$422.7	0.51
FY2015	267	100	162	5	5	6,296.4	0.042	\$547.3	0.49
FY2016	327	103	220	4	4	6,504.0	0.050	\$684.4	0.48
FY2017	283	86	197	0	0	6,562.0	0.043	\$564.9	0.50
FY2018	173	50	122	1	1	6,600.8	0.026	\$527.4	0.33
FY2019***	89	36	53	0	0	3,040.0	0.029	\$226.6	0.39
5 Yr Average	253	82	168	3	3	6,421.3	0.039	\$549.3	0.46

* June 1st through May 31st

** Property Damage Only

*** June 1st through Oct 31st

Why Pilot CV for Work Zone?

- Maintenance on board with Pilot – willing to test technology on maintenance vehicle
- Quick deployment
- Open communications among stakeholders
- Easy access to troubleshoot equipment throughout pilot
- Effective coordination of work zone vehicle operations and evaluation vehicle





Connected Work Zone Pilot

Connected Work Zone Pilot Overview

- Project Team
 - Gannett Fleming, Iteris, Information Logistics, Drive Engineering
- Project Objectives
 - Evaluate DSRC mobile (OBU) technology
 - Evaluate Vehicle data feed for alerts into Waze and TripTalk
 - Operate with “**No interaction needed from Operator**”
- Operational Scenarios
 - Stationary Work Zone
 - Mobile Work Zone



Pilot Primary Tasks

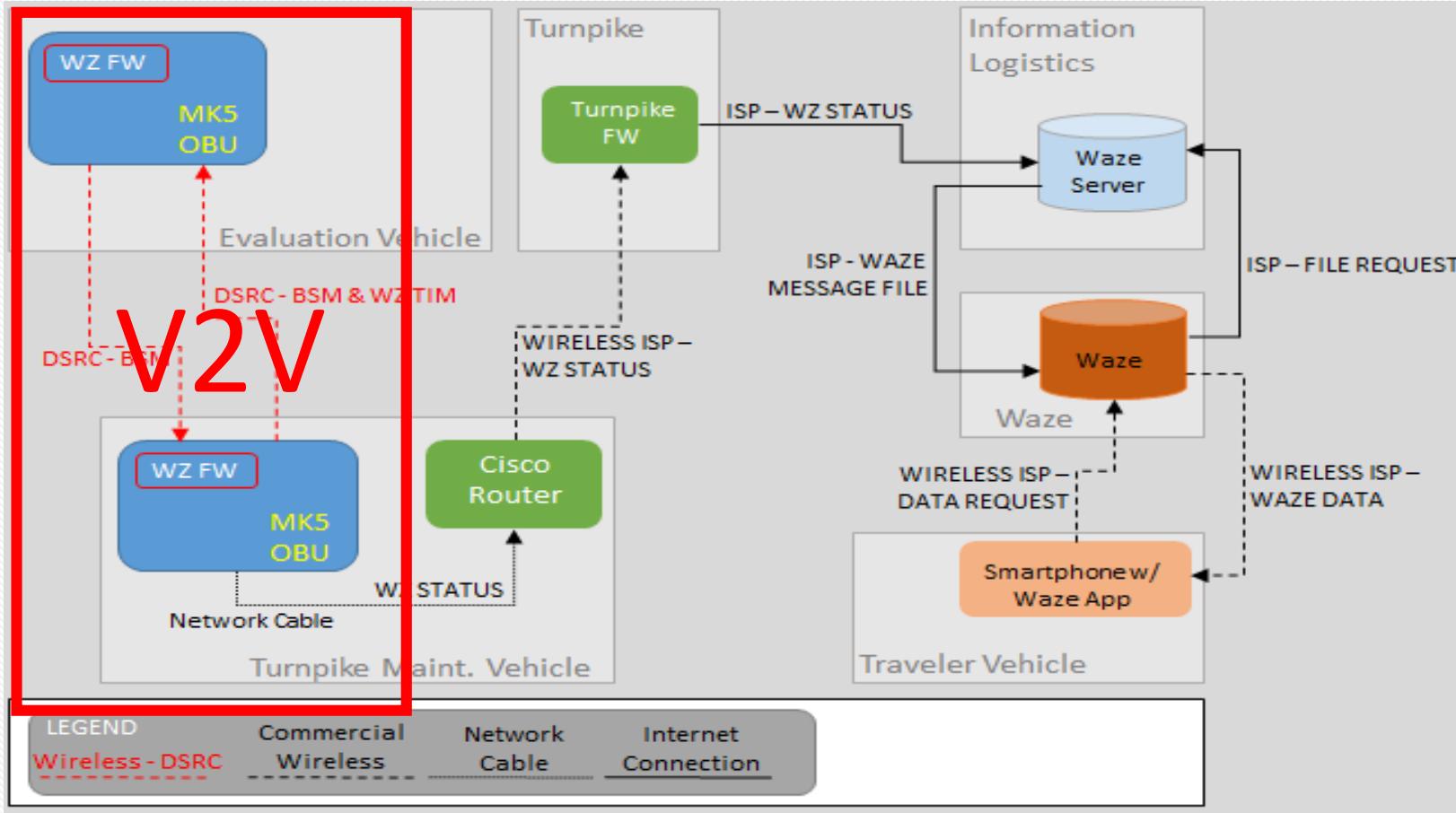
- Develop Conops, Requirements, System Design, Evaluation Plan
- Software / Firmware development
- Waze / TripTalk Application Integrations
- Hardware procurement / Installation
- Integration and Testing
- Evaluation

Evaluation Metrics

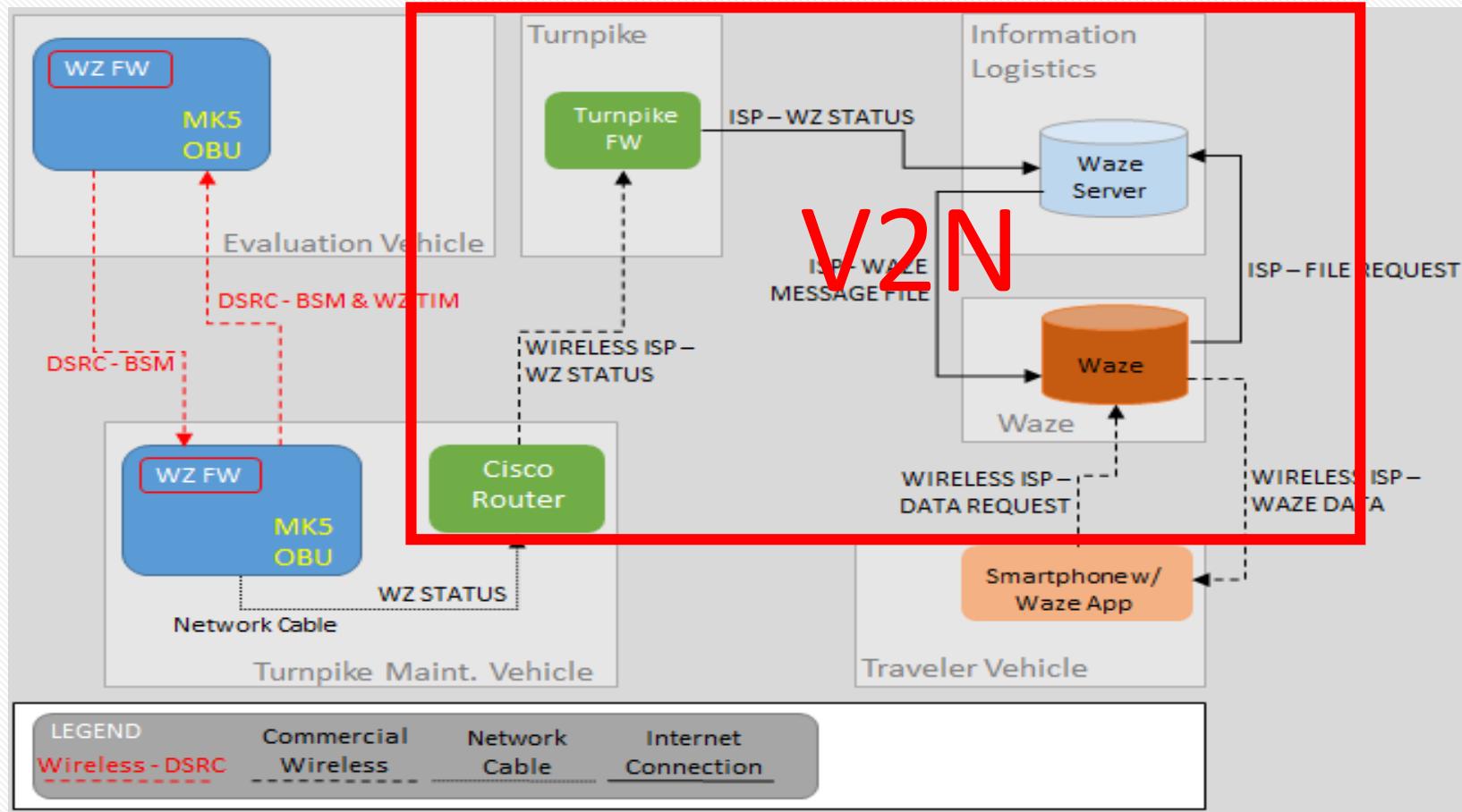
- What % of transmitted messages were received V2V, Waze & TripTalk?
- Distance from TMA that messages were disseminated V2V, Waze & TripTalk?
- Was messaging provided for relevant direction of travel?
- Message Latency?
- Number of vehicles equipped with DSRC capable devices on PTC that transmitted BSM?



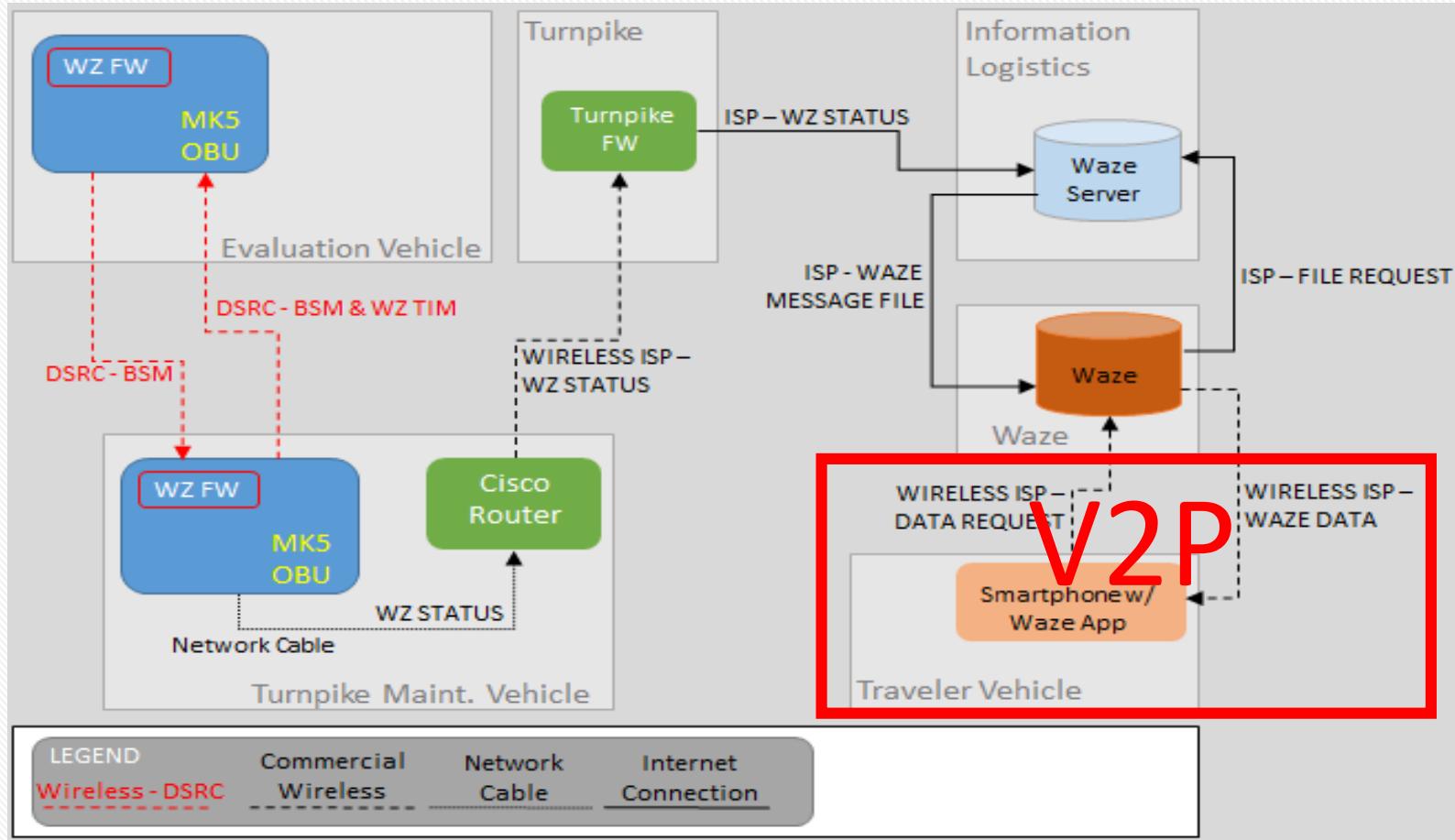
System Architecture



System Architecture



System Architecture





CV WZ implementation, Evaluation, Lessons Learned

Key Requirements

- OBU application is on at all times in maintenance zone
- OBU application sends simple messages when
 - Vehicle in preconfigured geofence of maintenance zone
 - Vehicle moving slowly or stopped
 - ~~Time during preconfigured construction schedule~~
- V2V Communication between maintenance vehicle and evaluation or OBU-equipped vehicle (via DSRC)
 - Implemented using Roadside Alert
- Communication to ILog for Waze via wireless ISP over Internet*
 - OBU application provides alert information to servers
 - Servers generate CIFS 2.0 message every 30 seconds
 - Servers terminate message with comm failure from OBU

* Communication for Trip Talk App added

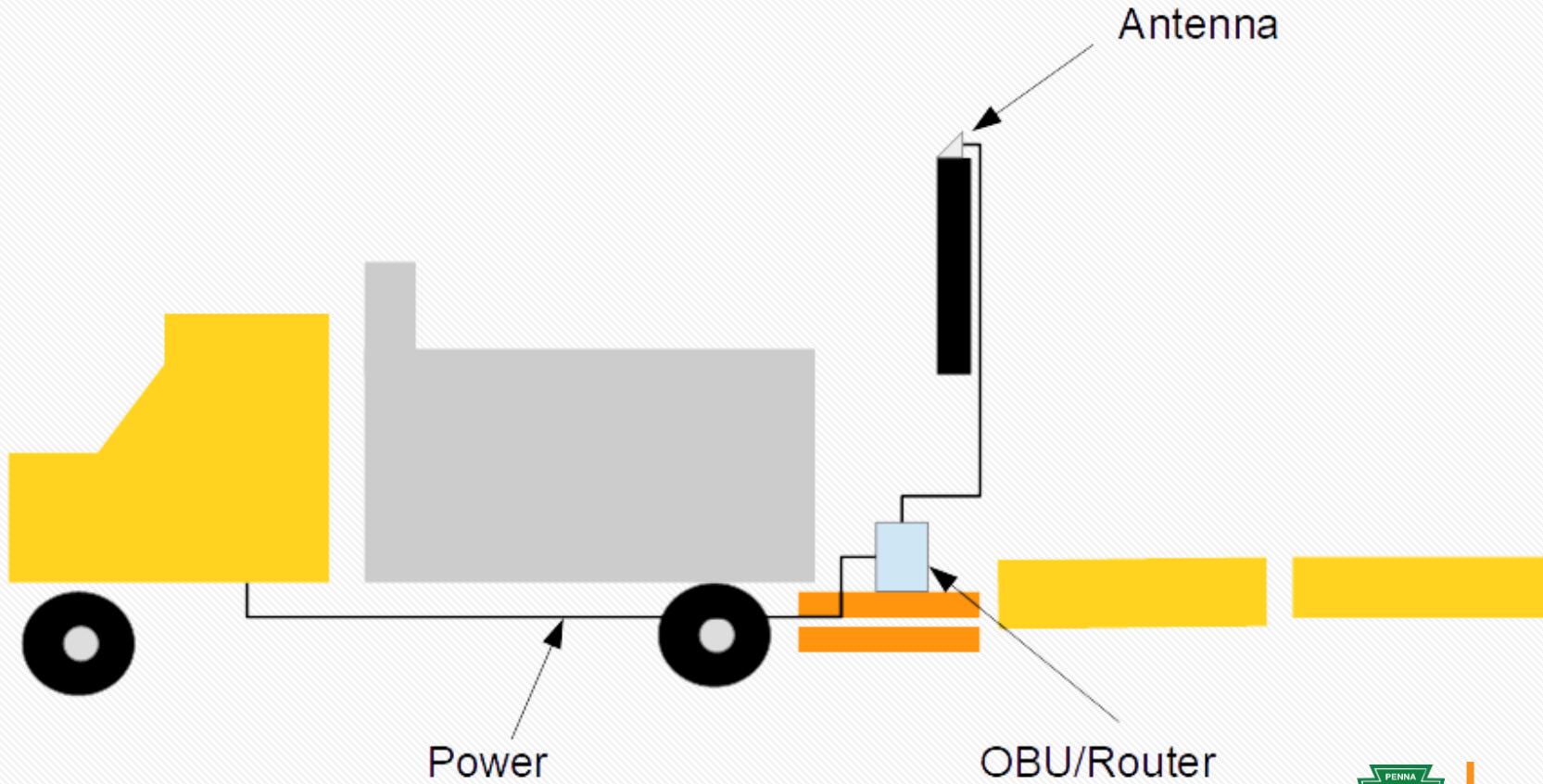


Project Hardware

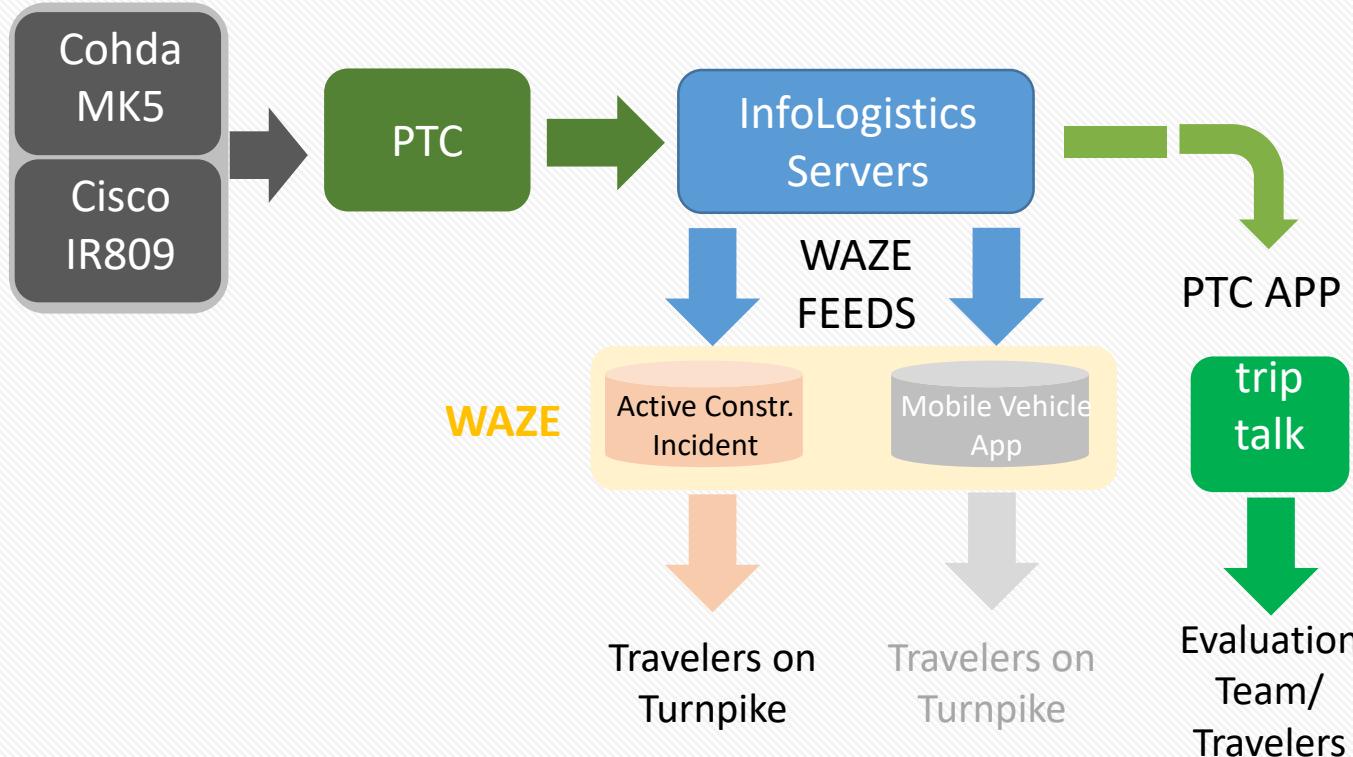


Enclosure Design/ Equipment Install by
Gannet Fleming

OBU Installation



Task 4.3 Operational Evaluation (WAN feeds)



Evaluation Hardware



Project Status

- Initiated December 2017
- OBU and router installed on maintenance vehicle in June 2018
- OBU firmware last updated in August 2018
- System in operation during routine maintenance activities starting in August
- Notification via Waze incomplete
 - Alerts being retrieved by Waze servers
 - Alerts not displayed on Waze app or website map
- Evaluation of information display using mobile phone app using Trip Talk in place of Waze
 - Alerts successfully displayed on Turnpike's Trip Talk app



Evaluation Metrics

- What % of transmitted messages were received V2V, Waze & TripTalk?
 - V2V - 100%
 - TripTalk - 83%
 - Waze - 0%
 - No false alarms
- Distance from TMA that messages were disseminated V2V, Waze & TripTalk?
 - V2V – 0.1 - 0.2 miles
 - TripTalk – 0.4 - 1.2 miles
 - Waze – N/A
- Was messaging provided for relevant direction of travel?
 - V2V – 100% for moving WZ, unreliable for stationary
 - TripTalk – >90%
 - Waze – N/A



Evaluation Metrics (Cont.)

- Message Advance Warning?
 - V2V – ~15 seconds prior to encounter
 - TripTalk – ~60 seconds prior to encounter
 - Waze – N/A
- Number of vehicles equipped with DSRC capable devices on PTC that transmitted BSM?
 - 2 on Penn Turnpike in ~20 hours of TMA operation during evaluation
 - 2 additional off Penn Turnpike by evaluation vehicle en route

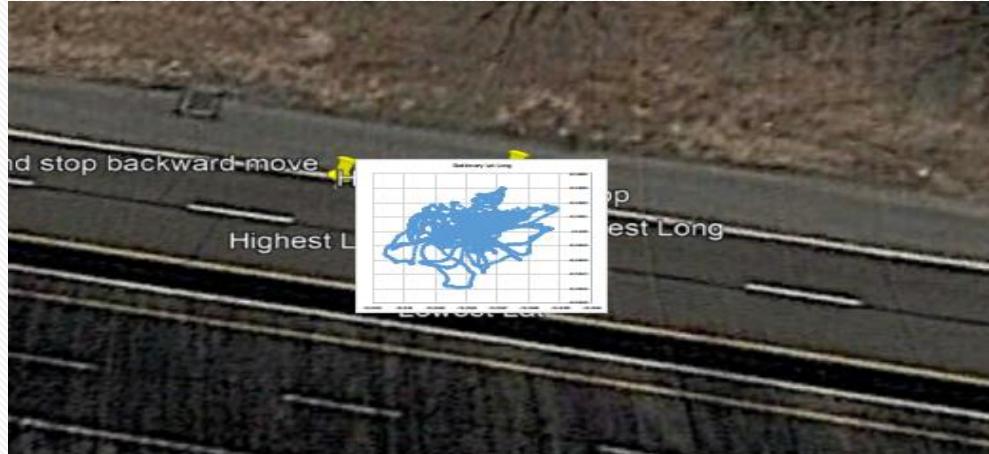


Lessons Learned

- Initial implementation handles vast majority of work zone situations correctly
- CV-DSRC stable platform for providing near real-time moving vehicle/ work zone status
- CV-DSRC-based system reliably provides data for use by mobile phone travel apps
- CV-DSRC can be integrated with commonly used wireless gateway for wide area communications
- Cohda OBU powerful Linux computer
 - Capable of mapping applications not included in pilot

Lessons Learned (Cont.)

- Installation approach (system on when ignition on) highly reliable
 - No resistance from operations
- GPS solutions not sufficiently reliable at lane level (as configured for this pilot)
 - GPS solution confidence may be able to determine when insufficiently accurate



Lessons Learned (Cont.)

- Need to evaluate design trade-offs with regard to work crew intervention
 1. No intervention (this pilot)
 - More sophisticated logic required for some situations
 - Maintenance vehicle on overpass
 - Maintenance vehicle in nearby service area
 - Maintenance vehicle reversing to stop
 2. Crew/Driver Activation
 - Adds one more thing for crew to do
 - Less risk of errors due to omissions in programming

Questions??



Michael Pack

mpack@paturnpike.com

Dwight Shank

des2@iteris.com