

# PA Turnpike Connected Work Zone Pilot



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# Agenda

- PA Turnpike CAV Roadmap – Selection of CV Pilot
- Connected Work Zone Pilot
  - Architecture
  - Evaluation Metrics
  - Installation and Integrations
  - Evaluation Preliminary Findings
  - Lessons Learned



# CAV Roadmap

# CAV Roadmap Project

- Project executed February 2016
- Prime – AECOM
- Subs – Information Logistics and TTI
- Roadmap Tasks:
  - Research current standards and best practices
  - Identify potential projects for short/mid/long term
  - Align with capabilities of PTC infrastructure readiness, planned projects, and in-house capabilities
  - Develop Implementation plan, starting with a “Quick Win” project
- Roadmap completed April 2017
- Executed CV pilot project December 2017

# Application Areas

## V2I Safety

Red Light Violation Warning  
Curve Speed Warning  
Stop Sign Gap Assist  
Spot Weather Impact Warning  
Reduced Speed/Work Zone Warning  
Pedestrian in Signalized Crosswalk  
Warning (Transit)

## V2V Safety

Emergency Electronic Brake Lights (EEBL)  
Forward Collision Warning (FCW)  
Intersection Movement Assist (IMA)  
Left Turn Assist (LTA)  
Blind Spot/Lane Change Warning  
(BSW/LCW)  
Do Not Pass Warning (DNPW)  
Vehicle Turning Right in Front of Bus  
Warning (Transit)

## Road Weather

Motorist Advisories and Warnings (MAW)  
Enhanced MDSS  
Vehicle Data Translator (VDT)  
Weather Response Traffic Information  
(WxTINFO)

## Environment

Eco-Approach and Departure at  
Signalized Intersections  
Eco-Traffic Signal Timing  
Eco-Traffic Signal Priority  
Connected Eco-Driving  
Wireless Inductive/Resonance Charging  
Eco-Lanes Management  
Eco-Speed Harmonization  
Eco-Cooperative Adaptive Cruise Control  
Eco-Traveler Information  
Eco-Ramp Metering  
Low Emissions Zone Management  
AFV Charging / Fueling Information  
Eco-Smart Parking  
Dynamic Eco-Routing (light vehicle,  
transit, freight)  
Eco-ICM Decision Support System

## Agency Data

Probe-based Pavement Maintenance  
Probe-enabled Traffic Monitoring  
Vehicle Classification-based Traffic  
Studies  
CV-enabled Turning Movement &  
Intersection Analysis  
CV-enabled Origin-Destination Studies

## Mobility

Advanced Traveler Information System  
Intelligent Traffic Signal System  
(I-SIG)  
Signal Priority (transit, freight)  
Mobile Accessible Pedestrian Signal System  
(PED-SIG)  
Emergency Vehicle Preemption (PREEMPT)  
Dynamic Speed Harmonization (SPD-HARM)  
Queue Warning (Q-WARN)  
Cooperative Adaptive Cruise Control (CACC)  
Incident Scene Pre-Arrival Staging Guidance  
for Emergency Responders (RESP-STG)  
Incident Scene Work Zone Alerts for Drivers  
and Workers (INC-ZONE)  
Emergency Communications and Evacuation  
(EVAC)  
Connection Protection (T-CONNECT)  
Dynamic Transit Operations (T-DISP)  
Dynamic Ridesharing (D-RIDE)  
Freight-Specific Dynamic Travel Planning and  
Performance  
Drayage Optimization

## Smart Roadside

Wireless Inspection  
Smart Truck Parking

# Connected vs Autonomous

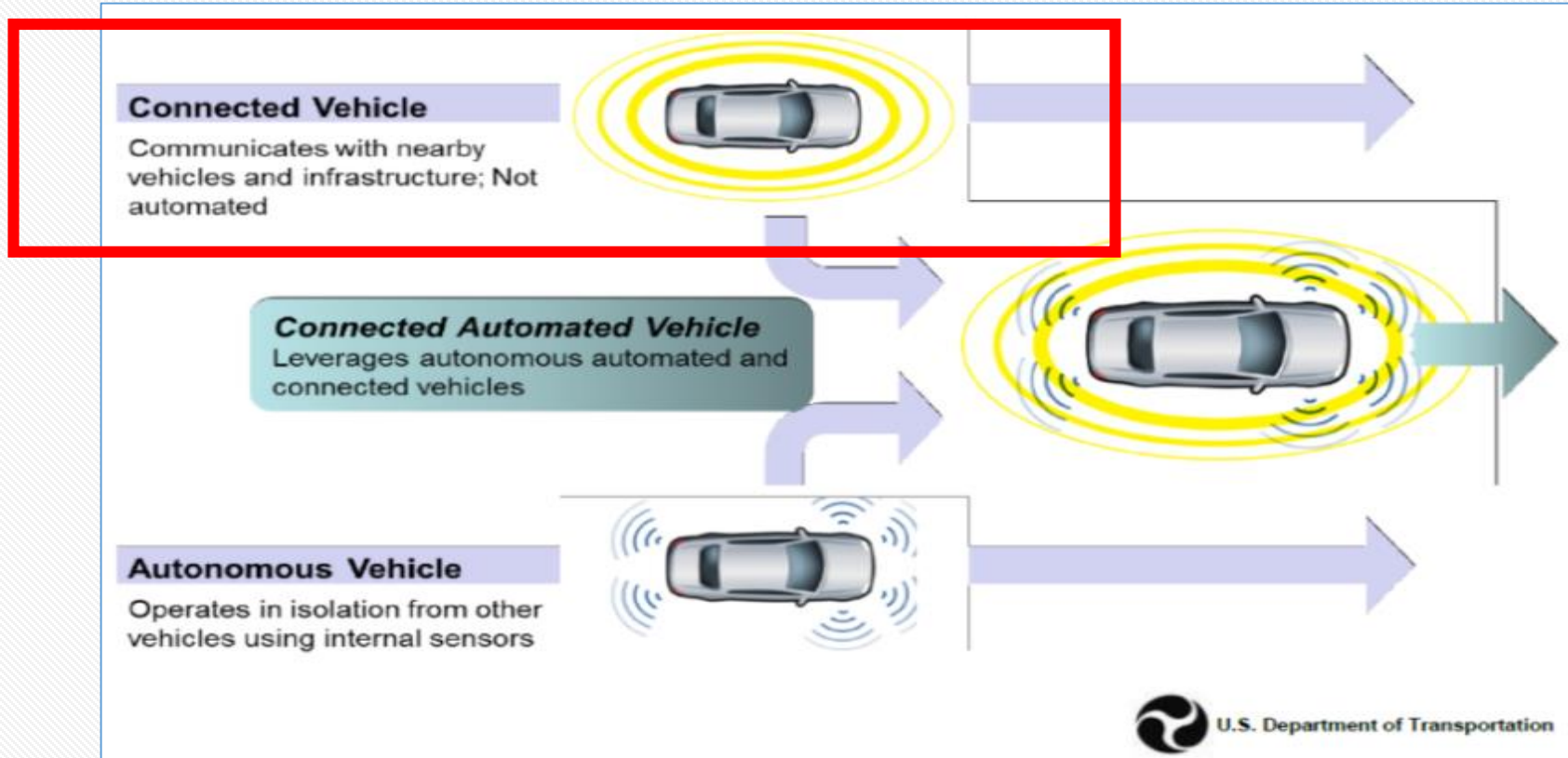


Figure 1. What are Connected and Automated Vehicles?

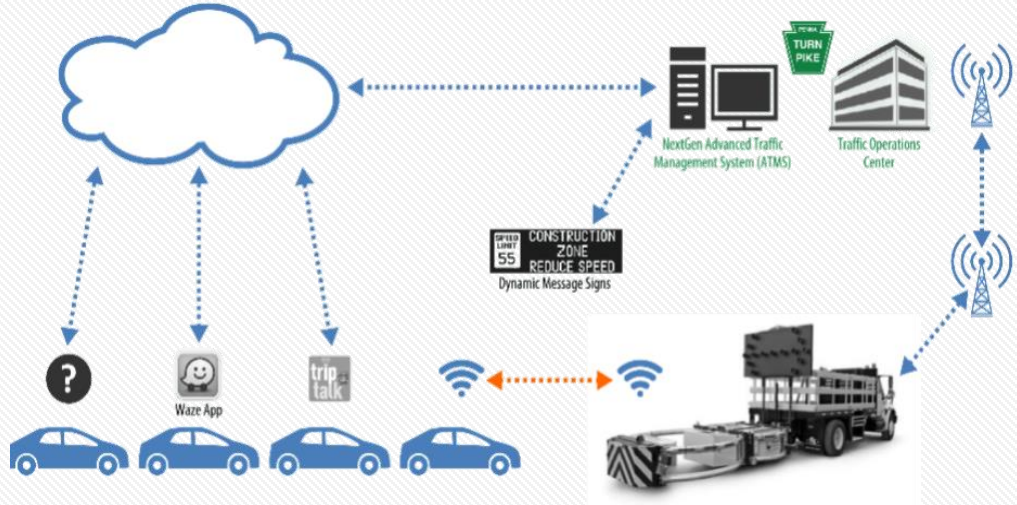
# CV Top Priorities

Weather

Traffic Incident Management

Safety

Work Zones



# CV Deployment Plan

## Short-Term

0-4 Years ▼

- Warnings about Upcoming Work Zone (Work Zone Safety)
- Advanced Traveler Information Systems (Traveler Information)
- Incident Scene Work Zone Alerts for Drivers and Workers (Traffic Incident Management)
- Electronic Toll Collection (Tolling)
- Reduced Speed Zone Warning/Lane Closure (Work Zone Safety)
- Traveler Information-Smart Parking (Traveler Information)
- Curve Speed Warning (Roadway Safety)
- Spot Weather Impact Warning (Road Weather Safety)

## Mid-Term

4-10 Years ▼

- Incident Scene Pre-Arrival Staging Guidance for Emergency Responders (Traffic Incident Management)
- Road Weather Information for Maintenance and Fleet Management Systems (Road Weather Safety)
- Variable Speed Limits for Weather-Responsive Traffic Management (Road Weather Safety)
- Road Weather Motorist Alert and Warning (Road Weather Safety)
- In-Vehicle Signage (Traveler Information)
- Queue Warning (Roadway Safety)
- Warnings about Hazards in a Work Zone (Work Zone Safety)

## Long-Term

Beyond 10 Years ▼

- Speed Harmonization (SPD-HARM) (Traffic Network)
- Road Use Charging (Congestion Pricing)
- Vehicle Data for Traffic Operations (Traffic Network)
- Performance Monitoring and Planning (Traffic Network)
- Enhanced Maintenance Decision Support System (Traffic Network)
- Advanced Automatic Crash Notification Relay (EVAC) (Traffic Incident Management)
- Road Weather Information and Routing Support for Emergency Responders (Traffic Incident Management)



# Short Term Projects – Quick Wins

## CAV Safety Core Focus Areas

## CV Applications

## “Quick Win” Projects

Work Zone Safety

Traffic Incident  
Management

Roadway Safety

Road Weather Safety

- ▶ Warnings about Upcoming Work Zone
- ▶ Incident Scene Work Zone Alerts for Drivers and Workers
- ▶ Reduced Speed Zone Warning/Lane Closure
- ▶ Curve Speed Warning
- ▶ Spot Weather Impact Warning

### Option 1 (Pick One):

Mobile and Maintenance Patterns Warning (Line Painting; MP 319-326; MP 202-206)

Curve and Ramp Warning Systems (Breezewood Interchange)

Road Weather Information Systems (Mile Marker 288)

### Option 2:

Connected Truck Mounted Attenuator Pilot

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# Why Pilot CV for Work Zone?

## Work Zone Crash Summary

Fiscal Year - Total\*

Fiscal Year	Work Zone Total Crashes			Work Zone Fatal Crashes		Vehicle Miles Traveled (Crashes per MVMT)		Capital Spending (Crashes per Million)	
	Total	Injury	PDO**	Total	Person	MVMT	Rate	Cost (M)	Rate
FY2014	214	70	141	3	3	6,143.3	0.035	\$422.7	0.51
FY2015	267	100	162	5	5	6,296.4	0.042	\$547.3	0.49
FY2016	327	103	220	4	4	6,504.0	0.050	\$684.4	0.48
FY2017	283	86	197	0	0	6,562.0	0.043	\$564.9	0.50
FY2018	173	50	122	1	1	6,600.8	0.026	\$527.4	0.33
FY2019***	89	36	53	0	0	3,040.0	0.029	\$226.6	0.39
5 Yr Average	253	82	168	3	3	6,421.3	0.039	\$549.3	0.46

\* June 1st through May 31st

\*\* Property Damage Only

\*\*\* June 1st through Oct 31st

# Why Pilot CV for Work Zone?

- Maintenance on board with Pilot – willing to test technology on maintenance vehicle
- Quick deployment
- Open communications among stakeholders
- Easy access to troubleshoot equipment throughout pilot
- Effective coordination of work zone vehicle operations and evaluation vehicle



# **Connected Work Zone Pilot**

# Connected Work Zone Pilot Overview

- Project Team
  - Gannett Fleming, Iteris, Information Logistics, Drive Engineering
- Project Objectives
  - Evaluate DSRC mobile (OBU) technology
  - Evaluate Vehicle data feed for alerts into Waze and TripTalk
  - Operate with “**No interaction needed from Operator**”
- Operational Scenarios
  - Stationary Work Zone
  - Mobile Work Zone

# Pilot Primary Tasks

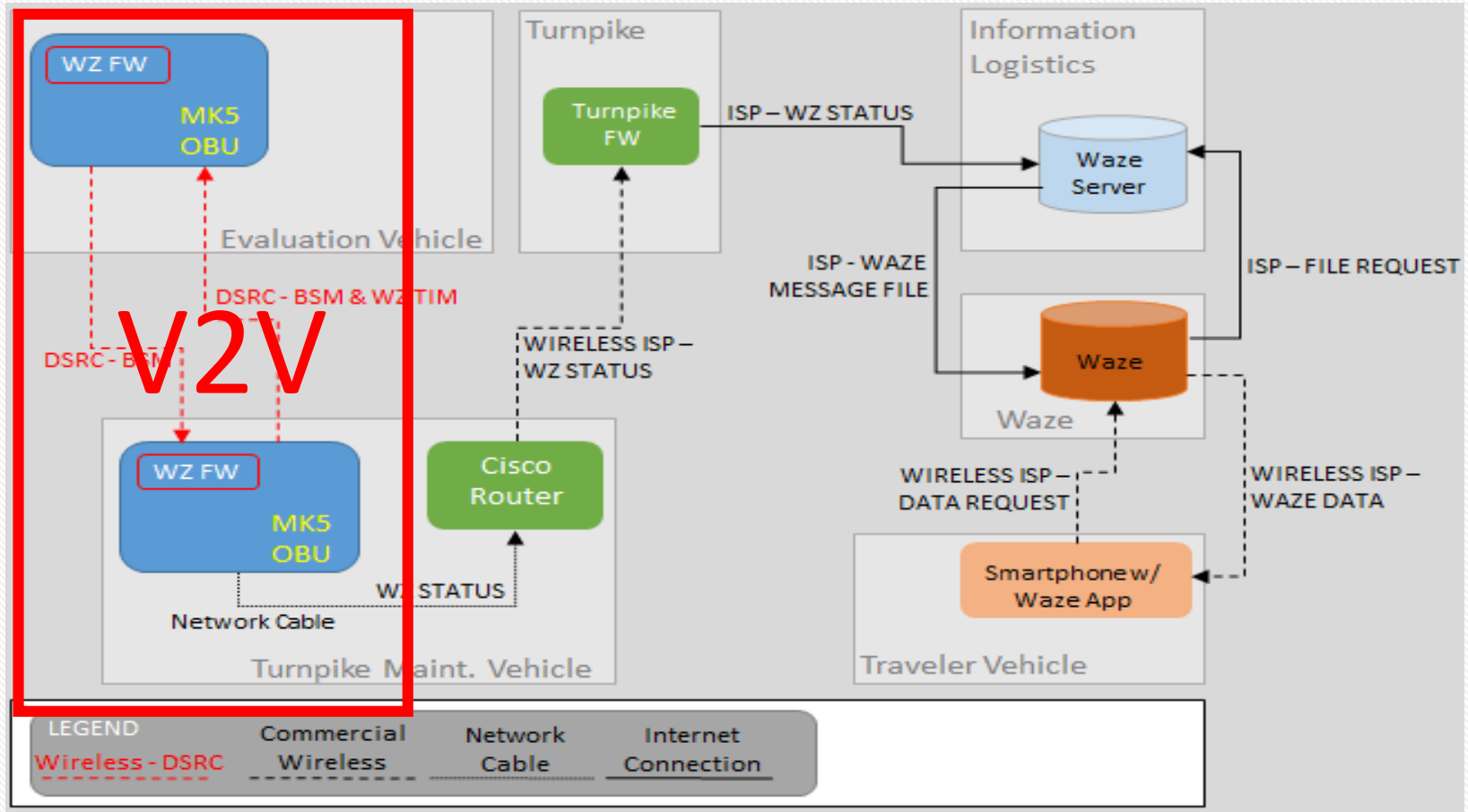
- Develop Conops, Requirements, System Design, Evaluation Plan
- Software / Firmware development
- Waze / TripTalk Application Integrations
- Hardware procurement / Installation
- Integration and Testing
- Evaluation

# Evaluation Metrics

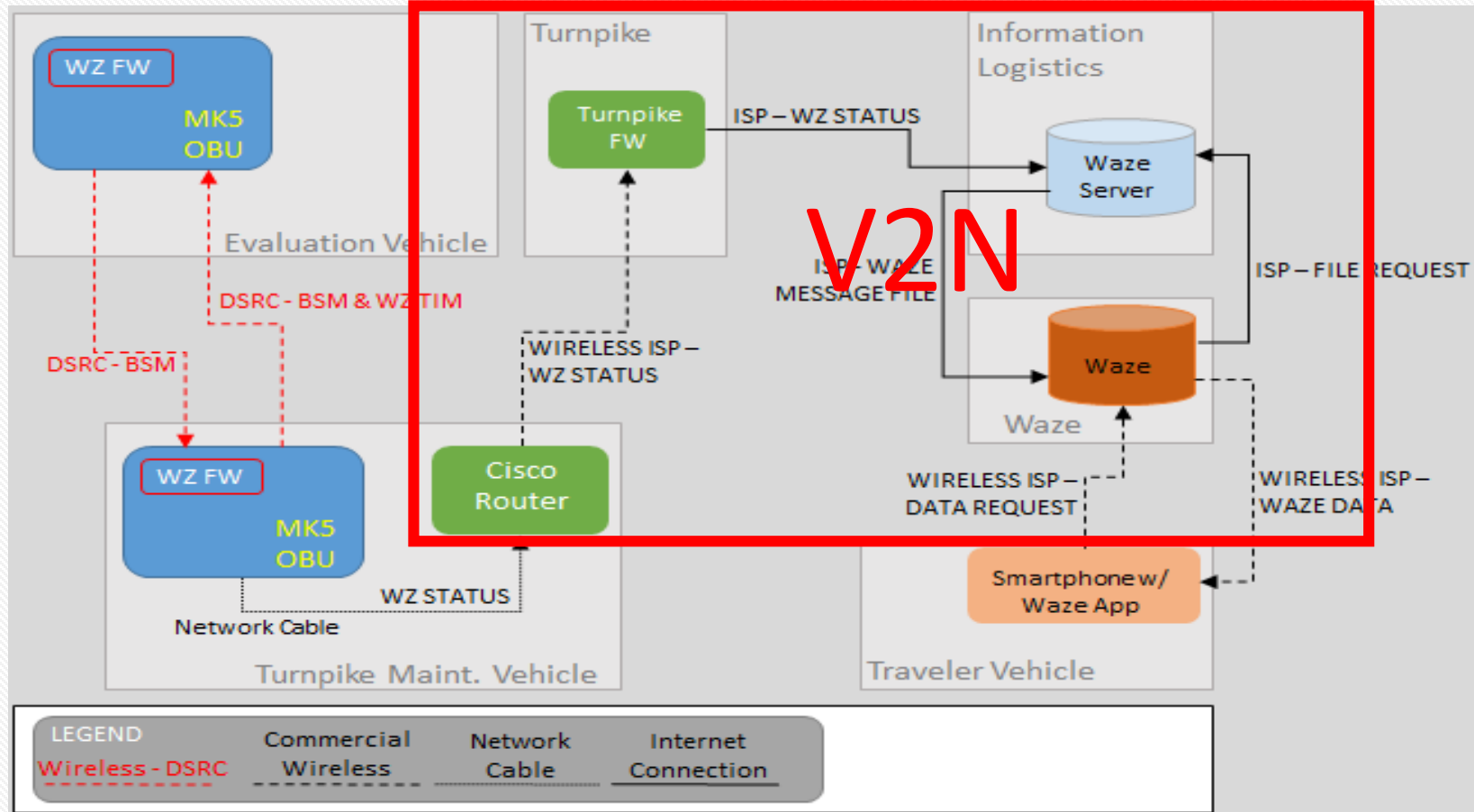
- What % of transmitted messages were received V2V, Waze & TripTalk?
- Distance from TMA that messages were disseminated V2V, Waze & TripTalk?
- Was messaging provided for relevant direction of travel?
- Message Latency?
- Number of vehicles equipped with DSRC capable devices on PTC that transmitted BSM?



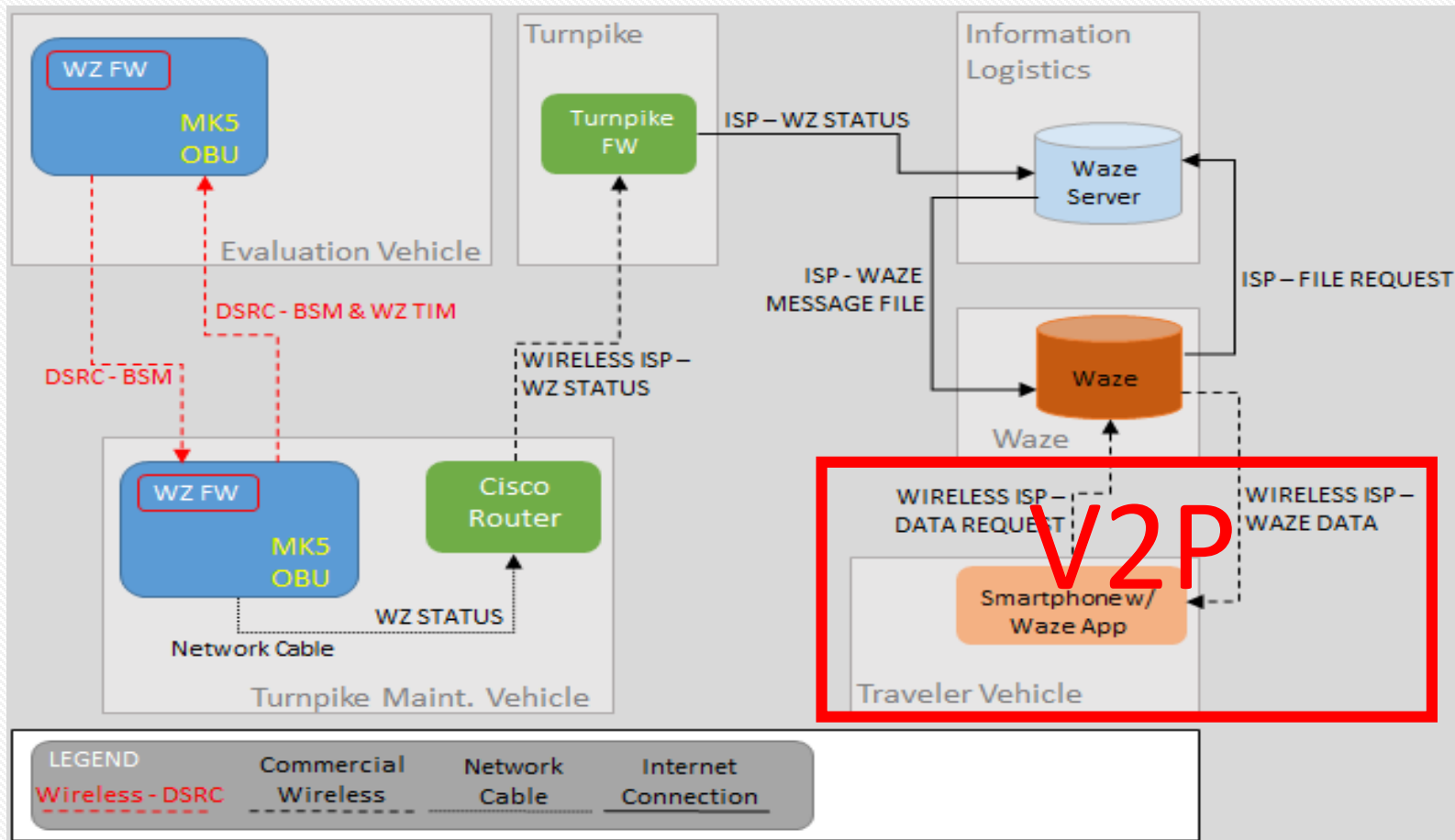
# System Architecture



# System Architecture



# System Architecture





# **CV WZ implementation, Evaluation, Lessons Learned**

# Key Requirements

- OBU application is on at all times in maintenance zone
- OBU application sends simple messages when
  - Vehicle in preconfigured geofence of maintenance zone
  - Vehicle moving slowly or stopped
  - ~~Time during preconfigured construction schedule~~
- V2V Communication between maintenance vehicle and evaluation or OBU-equipped vehicle (via DSRC)
  - Implemented using Roadside Alert
- Communication to ILog for Waze via wireless ISP over Internet\*
  - OBU application provides alert information to servers
  - Servers generate CIFS 2.0 message every 30 seconds
  - Servers terminate message with comm failure from OBU

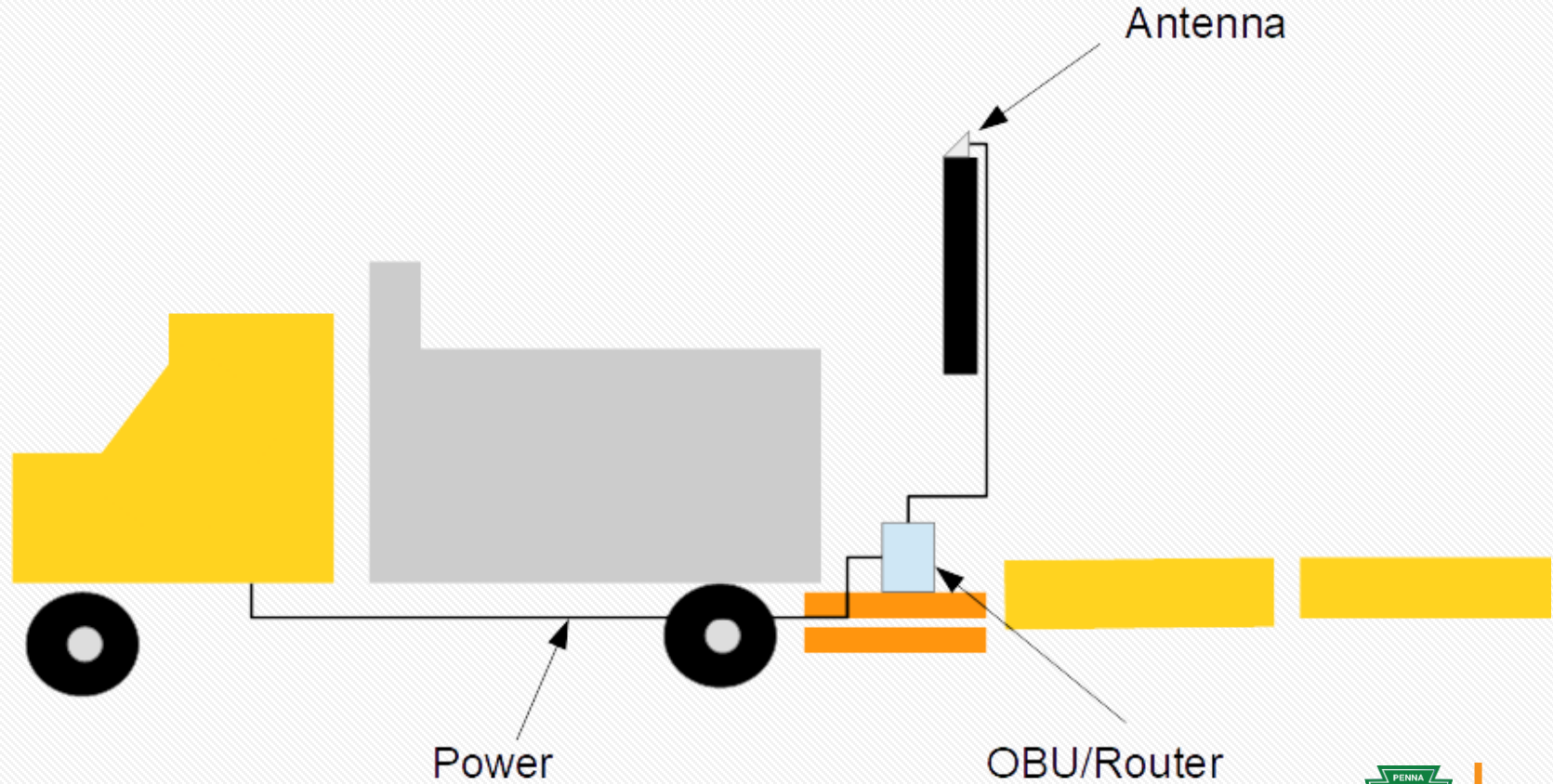
\* Communication for Trip Talk App added

# Project Hardware

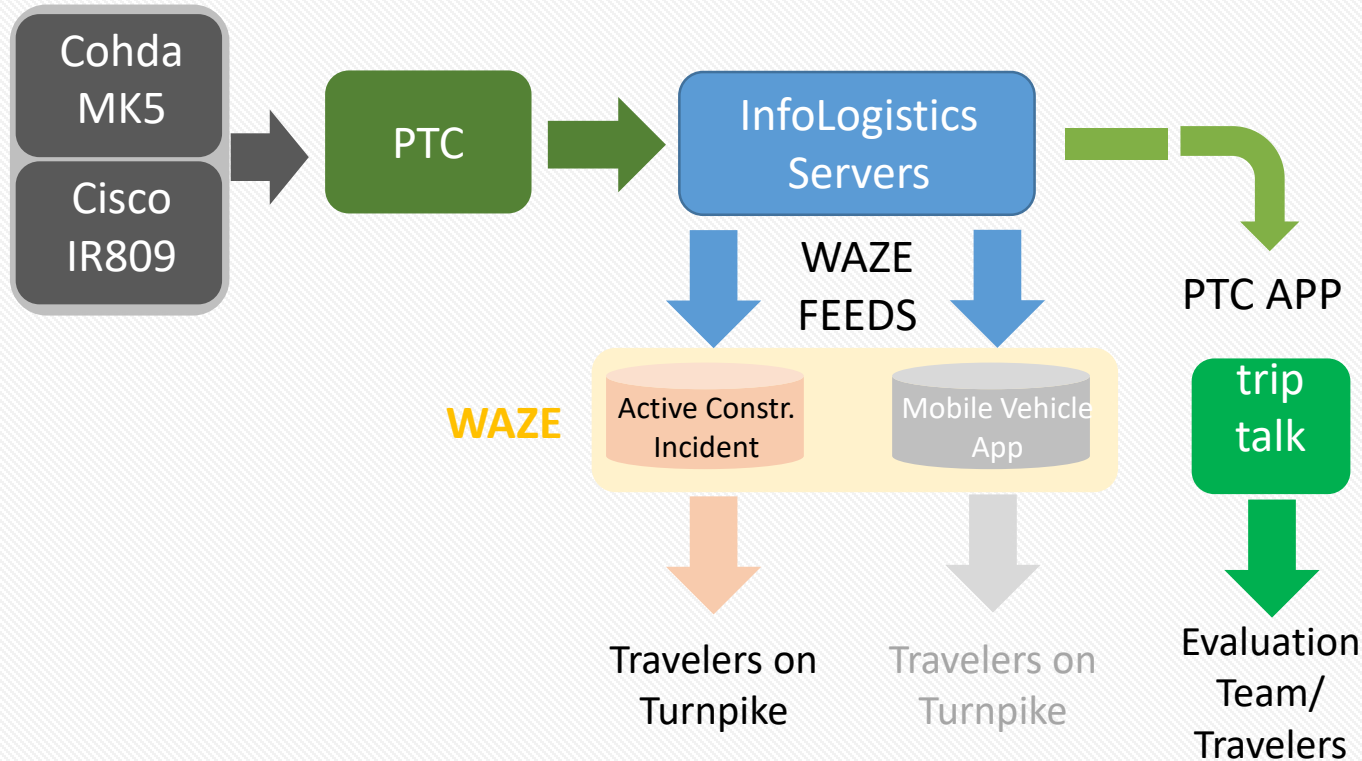


Enclosure Design/ Equipment Install by  
Gannet Fleming

# OBU Installation



# Task 4.3 Operational Evaluation (WAN feeds)





# Evaluation Hardware



# Project Status

- Initiated December 2017
- OBU and router installed on maintenance vehicle in June 2018
- OBU firmware last updated in August 2018
- System in operation during routine maintenance activities starting in August
- Notification via Waze incomplete
  - Alerts being retrieved by Waze servers
  - Alerts not displayed on Waze app or website map
- Evaluation of information display using mobile phone app using Trip Talk in place of Waze
  - Alerts successfully displayed on Turnpike's Trip Talk app

# Evaluation Metrics

- What % of transmitted messages were received V2V, Waze & TripTalk?
  - V2V - 100%
  - TripTalk - 83%
  - Waze - 0%
  - No false alarms
- Distance from TMA that messages were disseminated V2V, Waze & TripTalk?
  - V2V – 0.1 - 0.2 miles
  - TripTalk – 0.4 - 1.2 miles
  - Waze – N/A
- Was messaging provided for relevant direction of travel?
  - V2V – 100% for moving WZ, unreliable for stationary
  - TripTalk – >90%
  - Waze – N/A

# Evaluation Metrics (Cont.)

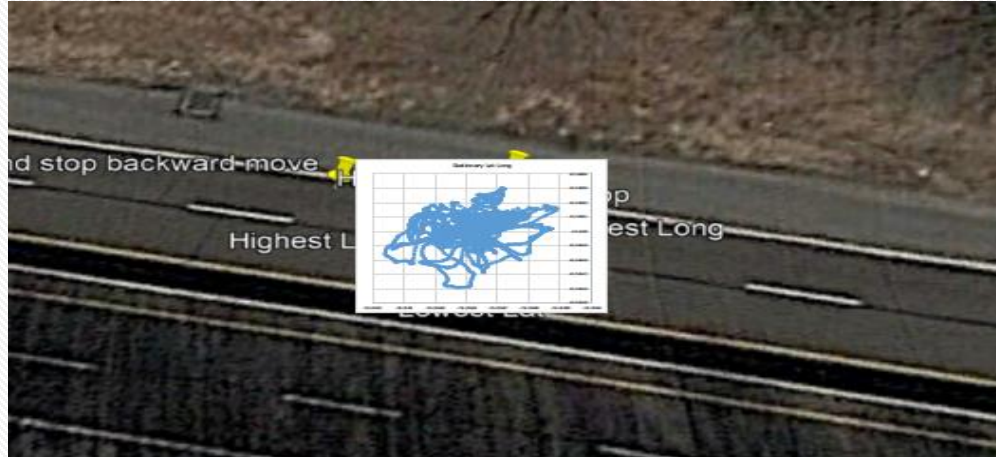
- Message Advance Warning?
  - V2V – ~15 seconds prior to encounter
  - TripTalk – ~60 seconds prior to encounter
  - Waze – N/A
- Number of vehicles equipped with DSRC capable devices on PTC that transmitted BSM?
  - 2 on Penn Turnpike in ~20 hours of TMA operation during evaluation
  - 2 additional off Penn Turnpike by evaluation vehicle en route

# Lessons Learned

- Initial implementation handles vast majority of work zone situations correctly
- CV-DSRC stable platform for providing near real-time moving vehicle/ work zone status
- CV-DSRC-based system reliably provides data for use by mobile phone travel apps
- CV-DSRC can be integrated with commonly used wireless gateway for wide area communications
- Cohda OBU powerful Linux computer
  - Capable of mapping applications not included in pilot

# Lessons Learned (Cont.)

- Installation approach (system on when ignition on) highly reliable
  - No resistance from operations
- GPS solutions not sufficiently reliable at lane level (as configured for this pilot)
  - GPS solution confidence may be able to determine when insufficiently accurate



# Lessons Learned (Cont.)

- Need to evaluate design trade-offs with regard to work crew intervention
  1. No intervention (this pilot)
    - More sophisticated logic required for some situations
      - Maintenance vehicle on overpass
      - Maintenance vehicle in nearby service area
      - Maintenance vehicle reversing to stop
  2. Crew/Driver Activation
    - Adds one more thing for crew to do
    - Less risk of errors due to omissions in programming

# Questions??



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